

# THE ABSTRACT TRANSPORTATION PROBLEM

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Much of this material will also appear in a forthcoming book, Foundations of Spatial Economics, Johns Hopkins Press (Baltimore: Johns Hopkins Press).

## THE ABSTRACT TRANSPORTATION PROBLEM\* AND ITS APPLICATION TO LOCATION THEORY\*

### I. Introduction

In this paper we generalize the Transportation problem of linear programming to the case of a possibly infinite number of sources and sinks.

~~Why bother to do this?~~ In the first place, there are many situations which appear naturally in the form of a continuum of origins or destinations. For example, the a natural model of the flow of farm products to household takes origins to be a continuous region of the surface of the Earth (the farm belt), and destination

~~why bother to do this?~~ In the first place, the surface of the Earth is a continuum, and we may always think of transportation as a re-distribution of mass from one portion of the surface to another.

Many Transportation problems appearing in the literature achieve their finite character by a lumping together of continua into a finite number of pieces, which are treated as points: for example, treating countries as single points in international trade models.

However, the possible realm of application of the abstract transportation model goes well beyond Transportation per se. It is well known that a wide variety of models - of resource allocation, scheduling, etc. - can be thrown into the Transportation format. Problems of the "caterer" form, for example, involve the redistribution of mass from one point in time to another. Since Time is a continuum, such problems are often most naturally formulated with a continuum of origins and destinations.

Again, there is an infinity of types of possible commodities or industrial processes; thus, a problem of the form, "How shall I distribute

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"assign my resources among various activities?" is again a problem with an infinity of sources and sinks. In the last part of this paper we shall apply the abstract transportation model to a problem of this form: the assignment of land among possible land-uses.

Although this paper is not concerned directly with numerical applications, one possible "practical-man's" objective should be laid to rest. It is not true that the abstract transportation model must be approximated finitely - by the lumping process mentioned above - to achieve numerical results.

What practice requires is that the set of possible answers be represented by a parameter space of relatively low dimension. This can be achieved by the lumping process, but can also be achieved in other ways, depending on the particular problem. This is illustrated by statistics, where continuous density distributions are put to practical use by working with families of them indexed by a small number of parameters.

## 2. Formulating the model

The Transportation problem with  $m$  sources and  $n$  sinks is -  
find  $m \times n$  non-negative numbers  $x_{ij}$  ( $i = 1 \dots m$ ,  $j = 1 \dots n$ )  
satisfying

$$(i) \quad \sum_j x_{ij} \leq a_i \quad (i = 1 \dots m), \quad (1)$$

$$(ii) \quad \sum_i x_{ij} \geq b_j \quad (j = 1 \dots n), \quad (2)$$

$$(3) \quad \text{and minimizing } \sum_{i,j} r_{ij} x_{ij}, \quad (3)$$

Here  $a_i$  is the capacity of source  $i$ ,  $b_j$  is the requirement at sink  $j$ , and  $r_{ij}$  is the cost incurred per unit shipped from source  $i$  to sink  $j$ .

The natural generalization of this uses measures and integrals.

$x \in E$  signifies that  $x$  is a member, ~~within ECF~~, of  $E$ . S.t.  $E$  is contained in set  $F$ , iff every member of  $E$  is a member of  $F$ .

We now define the necessary concepts.

'This paper is self-contained so far as definitions go, but standard theorems are quoted without proof.'

no 91 The union of sets  $E$  and  $F$ , written  $E \cup F$ , is the set whose ~~points~~ <sup>members</sup> are members of  $E$  or  $F$  or both. More generally, if  $\mathcal{G}$  is an arbitrary collection of sets, its union, written  $\bigcup \mathcal{G}$ , is the set whose ~~points~~ <sup>members</sup> are members of at least one of the sets of  $\mathcal{G}$ . The intersection of sets  $E$  and  $F$ , within  $E \cap F$ , is the set whose ~~points~~ <sup>members</sup> are members of both  $E$  and  $F$ . If  $\mathcal{G}$  is an arbitrary collection of sets, its intersection, written  $\bigcap \mathcal{G}$ , is the set whose ~~members~~ <sup>points</sup> are members of all of the  $\mathcal{G}$ -sets.

no 92 The difference of sets  $E$  and  $F$ , written  $E \setminus F$ , is the set whose ~~points~~ <sup>members</sup> are members of  $E$  but not of  $F$ .

The complement of set  $F$  in set  $E$ , written  $E \setminus F$ , is the set whose ~~points~~ <sup>members</sup> are members of  $E$  but not of  $F$ . The empty set, written  $\emptyset$ , is the set which has no members. A set  $E$  is countable iff its members can be enumerated in a finite or infinite sequence  $\{e_1, e_2, \dots\}$ .

Let  $A$  be a fixed set, and  $\Sigma$  a collection of subsets of  $A$ ;  $\Sigma$  is a sigma-field over  $A$  iff (1)  $A \in \Sigma$ , and (2) if  $E \in \Sigma$ , then  $(A \setminus E) \in \Sigma$ , and (3) if  $\mathcal{G}$  is any countable collection of  $\Sigma$ -sets, then  $\bigcup \mathcal{G} \in \Sigma$ . The pair  $(A, \Sigma)$  is called a measurable space, and the members of  $\Sigma$  are called measurable sets.

Let  $(A, \Sigma')$  and  $(B, \Sigma'')$  be two measurable spaces. The product measurable space, written  $(A \times B, \Sigma' \times \Sigma'')$  is defined as follows.  $A \times B$  is the cartesian product of  $A$  and  $B$ , the set of all ordered pairs  $(x, y)$ ,  $(x \in A, y \in B)$ . Any subset of  $A \times B$  of the form  $E \times F$ ,  $(E \in \Sigma', F \in \Sigma'')$  is called a measurable rectangle.

(continued) <sup>2</sup> Th.  $\Sigma$  in this sentence stands for summation, not for a class of sets. The distinction will be clear from the context.

$\Sigma' \times \Sigma''$  is the class of all sets common to all sigma-fields over  $A \times B$ , which have all measurable rectangles as members.  $\Sigma' \times \Sigma''$  itself can be shown to be a sigma-field over  $A \times B$ , the sigma-field generated by the measurable rectangles.

A <sup>bounded</sup> non-negative function, whose domain is a sigma-field, is a measure iff  $\mu(\cup G_i) = \sum_{i=1}^{\infty} \mu(G_i)$  whenever  $G_i$  is a ~~not~~ countable collection  $\{G_1, G_2, G_3, \dots\}$  of <sup>measurable sets</sup> which are disjoint ( $G_m \cap G_n = \emptyset$  for all  $m \neq n$ ). <sup>2</sup> A probability on  $(A, \Sigma)$  is a measure with domain  $\Sigma$  for which  $\mu(A) = 1$ .

The notation  $\{x | \dots\}$  represents the set of all  $x$  having the property stated after the bar. For example,  $\{x | f(x) > c\}$  is the set of all  $x$  for which the value of a certain function  $f$  exceeds the number  $c$ . Given a measurable space  $(A, \Sigma)$ , a function  $f$  with domain  $A$  is said to be measurable iff the sets  $\{x | f(x) > c\}$  are measurable for all real numbers  $c$ . It can be shown that the substitution of " $>$ ", " $\leq$ ", and " $<$ " for " $>$ " in this definition yields the same set of functions.

If  $f$  is a <sup>bounded</sup> measurable non-negative function, and  $\mu$  a measure, both with respect to  $(A, \Sigma)$ , the integral of  $f$  with respect to  $\mu$ , written  $\int_A f d\mu$ , is defined as  $\int_0^\infty \mu\{\{x | f(x) > t\}\} dt$ ,

where the integral on the right is an ordinary Riemann integral of the indicated (monoton. decreasing) function of the real var. If  $f$  takes on negative values, we split it into its positive and negative parts:  $f(x) = \max(f(x), 0) - \max(-f(x), 0)$ , take the integral of each part, and subtract.<sup>3</sup>

<sup>3</sup> For further reading in measure theory, the reader is referred to P.R. Halmos, Measure Theory (Princeton: Van Nostrand, 1950).

We are now ready to formulate th. abstract Transportation problem:  
 Given two triples,  $(A, \Sigma^1, \mu^1)$  and  $(B, \Sigma^2, \mu^2)$ , and a real-valued function  $r$  with domain  $A \times B$ , there

- (1)  $\Sigma^1$  is a sigma-field over set  $A$ , and  $\mu^1$  is a measure on  $\Sigma^1$ ; and similarly for  $\Sigma^2$ ,  $B$ , and  $\mu^2$ ;
- (2)  $r$  is bounded, and measurable, with respect to th. product sigma-field  $\Sigma^1 \times \Sigma^2$  over  $A \times B$ ;

find a measure  $\phi$  on  $(A \times B, \Sigma^1 \times \Sigma^2)$  which satisfies

$$\phi(E \times B) \leq \mu^1(E) \quad \text{for all } E \in \Sigma^1, \quad (4)$$

$$\phi(A \times F) \geq \mu^2(F) \quad \text{for all } F \in \Sigma^2, \quad (5)$$

and which minimizes  $\int_{A \times B} r d\phi$  over all such measures. (6).

This bears direct comparison with th. finite transportation problem

- (1), (2), (3).  $A$  and  $B$  ar. th. origin and destination spaces, respectively.  $\mu^1$  is th. capacity measure. Th. constraint (4), which is a direct generalization of (1), states tht  $\phi(E \times B)$ , which is the total flow of out of region  $E$ , cannot exceed  $\mu^1(E)$ , th. capacity of th. sources in region  $E$ .  $\mu^2$  is th. requirement measure, and (5), th. generalization of (2), states tht  $\phi(A \times F)$ , th. total inflow into region  $F$ , must at least meet th. requirement by th. region,  $\mu^2(F)$ .  $\phi$  is th. unknown flow from origin to destination:  $\phi(E \times F)$  equals th. total mass flowing from region  $E$  to region  $F$ .  $r$  generalizes th. unit cost function.

A careful check of the defining shows tht, in th. special case where  $A$  and  $B$  are finite sets, and  $\Sigma^1, \Sigma^2$  ar. th. classes of all subsets of  $A$  and  $B$ , respectively, (4), (5), (6) reduce to (1), (2), (3).

Before going on to th. analysis of th. abstract transportation problem,

Let us look at some related work. Martin Beckmann has worked on some related but non-overlapping problems.<sup>4</sup> Beckmann makes essential

"a continuous model of Transportation" Econometrica, 20: 643-660, October, 1952; "the partial equilibrium of a continuous space market," Weltwirtschaftliches Archiv, 71: 73-87, 1953

use of H<sub>2</sub> Topology of 2-dimensional Euclidean space, using vector methods (gradients, curls, etc.). In this sense, his is a special case of ours. On the other hand he deals with the intr. flow <sup>(and)</sup> paths, whereas we restrict our attention just to origin-destination conditions. Thus he is dealing essentially with a Transshipment, rather than a Transportation problem.

The <sup>abstract</sup> transshipment problem differs from the abstract transportation problem as follows: the spaces A and B, and the sigma-fields  $\Sigma'$  and  $\Sigma''$ , are identical; let us write them as  $(A, \Sigma)$ . There is a not requirement (signed) measure,  $\mu$ , on  $(A, \Sigma)$ . This differs from an ordinary measure only in that it may take on negative values. The constraints (4) and (5) are replaced by:

$$\phi(A \times E) - \phi(E \times A) \geq \mu(E) \quad \text{for all } E \in \Sigma. \quad (7)$$

The transshipment problem, then, is to find a new measure  $\phi$  on  $(A \times A, \Sigma \times \Sigma)$  which satisfies (7), and minimizes (6) over all such measures.

In the limit case there is a well known procedure for reducing transshipment to transportation problems.<sup>5</sup> This procedure breaks down

<sup>4</sup>A. Orden, "The transshipment problem", Management Science, 2: 276-285, April, 1956

when the number of sites in  $\Sigma$  is infinite. The Transshipment problem is essentially distinct<sup>(6)</sup> (and more difficult) than the Transportation problem in the general case. We shall concentrate our attention on the latter; it should be pointed out, however, that several of the theorems we derive have analogs for the Transshipment problem.

The true locus classicus for the abstract Transportation problem is found in the work of L.V. Kantorovich.<sup>6</sup> He deals with the problem of (4)-(6)

<sup>6</sup> "On the Translocation of masses", Management Science, 5:1-4, October, 1958 (originally published in Doklady Nauk USSR, 37, #7-8, 1942-1943, 1942.)

except in two minor points: the constraints are taken to be equalities, and  $\{A_i\}$  is identified with  $\{B_j\}$ . (This last identification involves no real loss of generality, but can be misleading, as we shall see.) He discusses the existence of optimal solutions and their connection with "potentials" (that is, dual prices; in the Terminology which developed later a) Kantorovich's paper — a remarkable achievement for its time. Kantorovich's article is peculiar in several respects. It is all of three pages long, and written with extreme brevity and apparent haste. In fact, the major theorem — stating the existence of dual prices associated with an optimal flow — is ~~unstated~~, false, as one can show by a simple counterexample.<sup>7</sup>

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Institute  
7 Space contains 3 points  $x, y, z$ ; the capacity at point  $x$  equals  $a_1$ ; the requirement at point  $y$  equals  $a_2$ ; all other capacities and requirements equal zero;  $r(x,y) = 1$ ,  $r(y,z) = 1$ ,  $r(x,z) = 3$ ; all other  $r_{ij}$ 's arbitrary; the only feasible, hence optimal, flow is  $a_1$  unit from  $x$  to  $z$ ; there is no Kantorovich potential for this flow, since it

(The root of the error, by the way, lies in the fact that the constraints imposed are those of the Transportation problem, while the dual prices are defined in a way appropriate to the transshipment problem. If the unit cost function  $\phi$  violates the triangle inequality <sup>as it well might</sup>, one can get a counter-example, as Gouthot  $\gamma$  illustrates.)

Note More surprising is the fact that the method of proof used ~~for this theorem~~ appears to be insufficient to prove the corrected version of the Theorem.

Our aim in the bulk of this paper is to go over the ground sketched out by Kantorovich, to derive in a rigorous fashion conditions for the existence of optimal solutions, and to give a "pseudo-constructor" method for finding dual prices from an optimal solution.

### 3. Feasibility

We begin the investigation ~~of~~ of the abstract transportation problem, (4) - (6), with a simple feasibility result.

Theorem 1: There exists a feasible solution to the constraints (4), (5) iff  
 $\mu'(A) \geq \mu''(B)$ . (7)

Proof: If  $\phi$  is a feasible solution, then  $\mu'(A) \geq \phi(A \times B) \geq \mu''(B)$ , so the stated condition is necessary.

Conversely, let  $\mu'(A) \geq \mu''(B)$ ; if  $\mu'(A) = 0$ , both  $\mu'$  and  $\mu''$  are identically zero, and thus the identically zero measure on  $\Sigma' \times \Sigma''$  is obviously feasible. If  $\mu'(A) > 0$ , define the function  $\phi$  on measurable rectangles  $E \times F$  by:  $\phi(E \times F) = \frac{\mu'(E) \cdot \mu''(F)}{\mu'(A)}$ . (8)

It is a standard measure theorem that such a "product" function can be extended to a measure over the product space  $(A \times B, \Sigma' \times \Sigma'')$ .

One checks immediately that this measure is feasible, since

$$\phi(E \times B) = \frac{\mu'(E) \cdot \mu''(B)}{\mu'(A)} \leq \mu'(E), \text{ and}$$

$$\phi(A \times F) = \mu''(F).$$

QED

This may be stated: a feasible solution exists iff total capacity of sources at least matches total requirements of sinks. This well known result in the limit case thus carries over in general.

We are also interested in the abstract transportation problem in the case where the constraints in (4) and (5) are stated as equalities:

$$\phi(E \times B) = \mu'(E) \quad (\text{for all } E \in \Sigma'), \quad (4)$$

$$\phi(A \times F) = \mu''(F) \quad (\text{for all } F \in \Sigma''). \quad (5)$$

Theorem 2: If  $\mu'(A) = \mu''(B)$ , then any feasible solution to (4), (5) satisfying these constraints with equality (that is, it is in fact feasible to the strict constraints (6), (11)).

Proof: Suppose, for example, that some constraint in (4) is satisfied with strict inequality:  $\phi(G \times B) < \mu'(G)$  for some  $G \in \Sigma'$ ; then

$$\mu''(B) \leq \phi(A \times B) = \phi(G \times B) + \phi((A \setminus G) \times B) < \mu'(G) + \mu'(A \setminus G) = \mu'(A),$$

a contradiction. The proof for  $\phi(A \times F) < \mu''(F)$  is similar. QED

We now have an equally simple feasibility result in this equality-constrained case:

Theorem 3: There exists a feasible solution to the constraints (6), (11), iff  $\mu'(A) = \mu''(B)$ . (12)

Proof: If  $\phi$  is feasible, then  $\mu'(A) = \phi(A \times B) = \mu''(B)$ .

If  $\mu'(A) = \mu''(B)$ , then Theorem 1 tells us that there is a feasible solution to (4) and (5), and Theorem 2 that these constraints are satisfied.

#### 4. Duality

Every finit. linear program has a dual, and th. dual of the Transportation problem (1) - (3) is & -

Find non-negative numbers  $p_i$  ( $i=1 \dots n$ ) and  $q_j$  ( $j=1 \dots n$ ) satisfying

$$q_j - p_i \leq r_{ij} \quad (i=1 \dots m; j=1 \dots n) \quad (13)$$

and maximizing:  $\sum_j q_j b_j - \sum_i p_i a_i$ . (14)

The dual of th. Transportation problem with equality constraints is &. same as this, except that  $p_i$  and  $q_j$  are not constrained to b. non-negative.

Analogously, we define the dual of th. abstract Transportation problem (4) - (6) to b. -

Find a bounded, non-negative, function,  $p$ , with domain A, measurable with respect to  $\Sigma'$ , and a bounded, non-negative, function,  $q$ , with domain B, measurable with respect to  $\Sigma''$ , satisfying

$$q(y) - p(x) \leq r(x, y) \quad \text{for all } x \in A, y \in B. \quad (15)$$

and maximizing:  $\int_B q d\mu'' - \int_A p d\mu'$ . (16)

The dual of th. abstract Transportation problem with equality constraints is defined to b. th. same as this, except that  $p$  and  $q$  need not be non-negative.

Apart from the obvious formal similarities between th. abstract duals and th. finite duals, many of th. standard relations between primal and dual carry over to th. general case. We first define m. more concepts.

Given a measure  $\phi$  on  $(A \times B, \Sigma^1 \times \Sigma^2)$ , its left-marginal measure,  $\phi'$ , is the measure defined on  $(A, \Sigma^1)$  by the rule:

$$\phi'(E) = \phi(E \times B), \quad \forall E \in \Sigma^1. \quad (17)$$

Similarly,  $\phi''$ , the right-marginal measure of  $\phi$ , is defined on  $(B, \Sigma^2)$  by the rule:

$$\phi''(F) = \phi(A \times F), \quad \forall F \in \Sigma^2. \quad (18)$$

(If  $\phi$  is a probability, its marginals coincide with the usual notion of marginal probabilities.) In terms of marginals, the basic transportation constraints (4) and (5) assume the simple form -

$$\phi' \leq \mu', \quad \text{and} \quad (19)$$

$$\phi'' \geq \mu''. \quad (20)$$

Theorem 4: If  $\phi$  is feasible for the abstract transportation problem, (4)-(5), and  $(p, q)$  is feasible for the dual, (15), then

$$\int_{A \times B} r d\phi \geq \int_B q d\mu'' - \int_A p d\mu'. \quad (21)$$

Proof: We adopt the simple convention that "p" stands both for a function with domain A, and for the function with domain  $A \times B$  defined by  $p(x, y) = p(x)$ ,  $\forall x \in A, \forall y \in B$ ; similarly, "q" stands for two functions with domains B, and  $A \times B$ , related by  $q(x, y) = q(y)$ ; which function we are talking about is clear from the domain of integration. Then

$$\begin{aligned} \int_{A \times B} r d\phi &\geq \int_{A \times B} (q - p) d\phi = \int_B q d\phi - \int_A p d\phi = \int_B q d\phi'' - \int_A p d\mu' \\ &\geq \int_B q d\mu'' - \int_A p d\mu'. \end{aligned} \quad (22)$$

(The first inequality follows from (15), the equality is the standard

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Integration Theorems, and the last inequality from (17) and (20), together with the fact that  $p$  and  $q$  are non-negative.) follows QED

Theorem 5: If  $\phi$  is feasible for the abstract transportation problem with equality constraints, and  $(p, q)$  is feasible for the dual of this problem, then (21) is still valid.

Proof: Same as above, except that the last " $\geq$ " should be replaced by " $=$ ". QED

These theorems carry over to the fact that, in a pair of linear programs, the value of the maximum program never exceeds the value of the minimum program, for any pair of feasible values.

We are now interested in conditions under which the inequality (4) becomes an equality, because, in view of Theorems 4 and 5, this would guarantee that  $\phi$ , and  $(p, q)$  are optimal for their respective programs.

Definition. Let  $\phi$  be feasible for the abstract Transportation problem (4)-(5), and  $(p, q) \stackrel{\geq 0}{\sim}$  feasible for the dual problem (15).  $(p, q)$  is a measure potential for  $\phi$  (and the disutility instead problem) iff the following three conditions are satisfied:

$$\phi \{ (x, y) | q(y) = p(x) \} = 0, \quad (22)$$

$$\phi \{ (x, y) | q(y) - p(x) < r(x, y) \} = 0, \quad (23)$$

$$\phi' \{ x | p(x) > 0 \} = \mu' \{ x | p(x) > 0 \}, \text{ and} \quad (24)$$

$$\phi'' \{ y | q(y) > 0 \} = \mu'' \{ y | q(y) > 0 \}. \quad (25)$$

(23) states that there is no flow on the set of source-sink pairs for which (15) is satisfied with strict inequality. (24) states that capacity

is used completely on the set of sources for which  $p > 0$ . (c) states that requirements are just met on the set of sinks for which  $q > 0$ .

The same definition also serves for the pair of equality-constrained programs, except that  $(p, q)$  need not be non-negative. Note also that for equality constraints, (24) and (25) are automatically fulfilled, so that they may be omitted from the definition.

Theorem 6: For a given feasible pair,  $\phi$  and  $(p, q)$ , relation (22) is an equality iff  $(p, q)$  is a measure potential for  $\phi$ . (This applies both to the inequality and the equality-constrained programs).

Proof: Examining the chain of relations (22), we find that the first " $\geq$ " becomes an equality iff (23) is fulfilled, and the last " $\geq$ " becomes an equality iff (24) and (25) are fulfilled. qed

Corollary: If  $\phi$  and  $(p, q)$  are feasible in their respective programs, and  $(p, q)\phi$  is a measure potential for  $\phi$ , then both are optimal to their programs.

The definition and Theorem 6 generalize the familiar "complementary slackness" conditions of linear programming, according to which equality is attained in dual program values iff strict inequality in one program's constraints is matched by a zero value of the corresponding variable in the other. The further (and deeper) condition in finite linear programming theory that "complementary slackness" is a necessary condition for optimality, does not necessarily carry over to the infinite case.

## 5. Existence of Optimal Solutions.

Up to this point, measure-theoretic concepts have sufficed to define our concepts and prove our theorems. From here on topological concepts will also be needed. Indeed, the author does not know of any method of proving the existence of optimal solutions to the abstract transportation problem using measure-theoretic concepts alone. Also, we know of no way to construct measure potentials directly from optimal solutions.

Instead we give a construction for the related notion of "topological potential", and under certain additional conditions this turns out to be measure potential as well. The basic definitions follow.

Given a fixed set  $A$ , let  $\mathcal{T}$  be a collection of subsets of  $A$ .  $\mathcal{T}$  is a topology over  $A$  iff (i)  $A \in \mathcal{T}$ , and the empty set  $\emptyset \in \mathcal{T}$ ; (ii) if  $G_1, G_2 \in \mathcal{T}$ , then  $G_1 \cap G_2 \in \mathcal{T}$ ; (iii) if  $\mathcal{G}$  is any collection of  $\mathcal{T}$ -sets, then  $\cup \mathcal{G} \in \mathcal{T}$ . The members of  $\mathcal{T}$  are called the open sets. A set is closed iff its complement in  $A$  is open.

Let  $(A, \mathcal{T})$  and  $(B, \mathcal{T}')$  be two topological spaces. The product topological space, written  $(A \times B, \mathcal{T}' \times \mathcal{T}'')$ , is defined as follows.  $A \times B$  is the cartesian product of  $A$  and  $B$ . Any subset of  $A \times B$  of the form  $G' \times G''$  ( $G' \in \mathcal{T}'$ ,  $G'' \in \mathcal{T}''$ ) is called an open rectangle.  $\mathcal{T}' \times \mathcal{T}''$  is the class of all sets which are unions of an arbitrary number of open rectangles, together with the empty set. It can be shown that  $\mathcal{T}' \times \mathcal{T}''$  is, indeed, a topology over  $A \times B$ .

A topological space  $(A, \mathcal{T})$  is separable iff there is a countable set  $E \subset A$  such that every non-empty open set has a member in common with  $E$ . A real-valued function  $f$  with domain  $A$  is continuous for the topology  $\mathcal{T}$  iff every set of the form  $\{x \mid a < f(x) < b\}$ , where  $a$  and  $b$  are real numbers, is open.

A metric on a set,  $A$ , is a real-valued function,  $d$ , with domain  $A \times A$ , having the properties (1)  $d(x, x) = 0$ ; (2)  ~~$d(x, y) > 0$  if  $x \neq y$~~  ; (3)  $d(x, y) = d(y, x)$ ; and (4)  $d(x, y) + d(y, z) \geq d(x, z)$ , for all  $x, y, z \in A$ . The pair  $(A, d)$  is a metric space. A sequence  $x_1, x_2, \dots$  in a metric space converges to  $x$  iff, for any positive number  $\epsilon$ , there is an integer  $N$ , such that  $d(x_n, x) < \epsilon$  for all  $n > N$ . A metric space is complete iff, for any sequence  $x_1, x_2, \dots$  having the property that  $d(x_m, x_n) < \epsilon$  whenever  $m$  and  $n$  exceed some integer  $N$ , depending on the positive number  $\epsilon$ , there is an  $x$  to which the sequence converges. (Roughly, when the points of a sequence get indefinitely close to each other, they get indefinitely close to some fixed point of the space.)

• Metric spaces: Any metric on  $A$  determines a Topology on  $A$  as follows: a set  $E \subset A$  is open iff, for every point  $x \in E$  there is a positive number  $\epsilon$  such that all points within distance  $\epsilon$  of  $x$  are members  $\text{of } E$ .

A Topology which is generated by some metric in this way is said to be metrizable. If it is generated by <sup>some</sup> complete metric it is said to be topologically complete. A set  $K$  in a metrizable Topological space  $(A, \mathcal{T})$  is compact iff any sequence of points members of  $K$  has a subsequence

which converges to a member of  $K$ . If the subsequence is entirely known to converge to a member of  $A$ , the set is relatively compact.

We will need certain concepts which involve set measure-

Theoretic and Topological notions. The Borel field of a Topological Space is the smallest sigma-field of which every open set is a member. (More exactly, it is the sigma-field to which a set belongs iff it belongs to every sigma-field to which all open sets belong.) The numbers

of the Borel field are called Borel sets. Let  $(A, \mathcal{T})$  be a metrizable topological space, let  $\Sigma$  be its Borel field, and let  $\mu$  be a measure on  $\Sigma$ .  $\mu$  is said to be tight iff, for every positive number  $\epsilon$ , there is a compact set  $K$  such that  $\mu(A \setminus K) < \epsilon$ . Let  $M$  be a collection of measures on  $\Sigma$ .  $M$  is uniformly tight iff (1) there is a number  $M$  such that  $\mu(A) \leq M$  for all measures  $\mu \in M$ , and (2) for every positive number  $\epsilon$  there is a compact set  $K$  such that  $\mu(A \setminus K) < \epsilon$  for all  $\mu \in M$ . (Note that this requires more than that each measure of  $M$  be individually tight.) Let  $\mu^*$  be a measure on  $\Sigma$ , and  $\mu_1, \mu_2, \dots$  a sequence of measures on  $\Sigma$ ; the sequence  $\mu_1, \mu_2, \dots$  is said to converge weakly to  $\mu^*$  iff, for every real-valued function  $f$  with domain  $A$  which is bounded, and continuous with respect to  $\mathcal{T}$ , we have

$$\lim_{n \rightarrow \infty} \int_A f d\mu_n = \int_A f d\mu^* \quad (26)$$

(in the ordinary sense of limit of a sequence of real numbers). The set of measures  $M$  is weakly relatively compact iff every sequence of measures in  $M$  contains a subsequence which converges weakly to some measure (not necessarily a member of  $M$ ).

Finally, we need one or two weitere concepts concerning real numbers. The supremum of a set of real numbers is the smallest number not exceeded by any of the numbers in the set; the infimum (inf) is the largest number which is not greater than any number of the set. (If the set has a greatest member, it is the supremum; similarly, if it has a least member, that member is the infimum.) Given a sequence of real numbers,  $x_1, x_2, \dots$ , let  $y_k$  be the supremum of the subsequence beginning with the  $k$ th term:  $x_k, x_{k+1}, \dots$ ; the limit of the sequence  $y_1, y_2, \dots$  formed in this way is called the  $\limsup$  of the original sequence.  $\liminf$  of the original sequence is defined

in the same way from the sequence of infima.

With these definitions taken care of, we are ready to proceed. The following two basic results from the theory of weak convergence play an essential role in our ~~exist~~<sup>8</sup> existence proofs.

<sup>8</sup>P. Billingsley, Convergence of Probability Measures (NY: Wiley, 1968), Chapter I, is a very clear exposition of the Theory. K.R. Parthasarathy, Probability Measures on Metric Spaces (NY: Academic Press, 1967), is also useful. (for the special case of probabilities).

Lemma 1: (Prohorov - Varadarajan) Let  $\mathcal{M}$  be a collection of measures on the Borel field of a metrizable topological space. If  $\mathcal{M}$  is uniformly tight, then  $\mathcal{M}$  is weakly relatively compact.

(A.D. Aleksandrov)

Lemma 2: The following three conditions are equivalent.

(a) The sequence  $\mu_1, \mu_2, \dots$  of measures in  $\mathcal{M}$  converge weakly to  $\mu^*$

(b)  $\limsup \mu_n(F) \leq \mu^*(F)$ , for every closed set  $F$ . (27)

(c)  $\liminf \mu_n(G) \geq \mu^*(G)$ , for every open set  $G$ . (28)

We are now ready to state our first existence theorem. For only in the case where total capacity equals total requirement, the abstract Transportation problem<sup>9</sup> To assess the practical scope of this theorem, it should be noted that  $N$ -dimensional Euclidean space is separable and topologically complete; thus the following theorem would appear to cover almost all cases to be met with in practice.

Theorem 7: Let  $(A, \Sigma', \mu')$  and  $(B, \Sigma'', \mu'')$ , and  $r$  be as in the abstract transportation problem, (a)-(b). In addition, assume that

$\Sigma' \Rightarrow \mathbb{M}$ , Borel field of a topology  $\mathcal{T}'$  over A, which is separable and topologically complete; similarly,  $\Sigma''$  is assumed to be the Borel field of a topology  $\mathcal{T}''$  over B, which is separable and topologically complete.  $r$  is also assumed to be continuous with respect to the product topology  $(A \times B, \mathcal{T}' \times \mathcal{T}'')$ . Finally, assume  $\mu'(A) = \mu''(B)$ .

Then there exists an optimal solution  $\phi^*$  to the abstract transportation problem.

Proof: There exists a feasible solution, by theorem 1. Also the set of values assumed by the objective function (6) is bounded, since  $r$  is bounded, and feasible  $\phi$ 's are bounded by constraint (4). Hence there exists a finite infimum,  $V$ , and a sequence of feasible flows,  $\phi_1, \phi_2, \dots$  such that

$$\lim_{n \rightarrow \infty} \int_{A \times B} r d\phi_n = V. \quad (22)$$

We will show that  $\phi_1, \phi_2, \dots$  converges weakly to an optimal measure. It is known that, in a separable and topologically complete space, any measure on the Borel field is tight (Ulam's theorem; see Billingsley, p5-6). Thus  $\mu'$  and  $\mu''$  are tight. Hence, for all positive  $\epsilon$ , there are compact sets  $K' \subset A$ ,  $K'' \subset B$ , such that  $\mu'(A \setminus K') < \epsilon$  and  $\mu''(B \setminus K'') < \epsilon$ .

Now  $K' \times K''$  is compact in the product topology (Tikhonov's theorem), and one verifies that, for any feasible  $\phi$ ,

$$\begin{aligned} \phi(A \times B \setminus K' \times K'') &\leq \phi(A \times (B \setminus K'')) + \phi((A \setminus K') \times B) \\ &= \mu''(B \setminus K'') + \mu'(A \setminus K') < 2\epsilon. \end{aligned} \quad (23)$$

(The equality in (23) follows from the fact that all constraints in (4) and (5) are actually equalities here - from theorem 2 above).

Hence the set of feasible solutions is uniformly tight. We now

apply Prohorov's Theorem (Lemma 1) to conclude that the set of feasible solutions is weakly relatively compact. (To justify this, we note that  $T' \times \mathcal{F}''$  is metrizable, since its components are, and  $\Sigma' \times \Sigma''$  is  $\text{TL}_c$ -Borel (recall that  $T' \times \mathcal{F}''$  since the latter are separable as well.)

Thus the sequence  $\Phi_1, \Phi_2, \dots$  contains a subsequence which converges weakly. For simplicity we use the same notation for this subsequence. It is clear that (2g) still applies to the subsequence. Letting  $\Phi^*$  be the weak limit of the subsequence, we obtain

$$\cancel{\Phi^*} \quad v = \lim_{n \rightarrow \infty} \int r d\Phi_n = \int r d\Phi^*, \quad (31)$$

from the definition of weak convergence. Thus  $\Phi^*$  attains the infimum, and we need only show that it is feasible to prove that it is optimal.

To prove feasibility, let  $\Phi'_n, \Phi''_n$ , and  $\Phi'^*, \Phi''^*$ , be the left and right marginal measures of  $\Phi_n$  and  $\Phi^*$ , respectively ( $n=1, 2, \dots$ ). The fact that  $\Phi_1, \Phi_2, \dots$  converges weakly to  $\Phi^*$  implies that  $\Phi'_1, \Phi'_2, \dots$  converges weakly to  $\Phi'^*$ , and similarly for the right-marginals. (Mann-Wald Theorem, see Billingsley, p30-31).

Now let  $G$  be any open subset of  $A$ . We obtain

$$\mu'(G) \geq \liminf \Phi'_n(G) \geq \Phi'^*(G). \quad (32)$$

(The first inequality comes from the fact that each measure  $\Phi_1, \Phi_2, \dots$  is feasible, hence satisfies (4); the second comes from Lemma 2.)

Similarly, let  $F$  be any closed subset of  $B$ . We obtain

$$\mu''(F) \leq \limsup \Phi''_n(F) \leq \Phi''^*(F). \quad (33)$$

~~(33)~~ shows It is known that the measure of any Borel set of a metrizable topological space equals the  $\text{TL}$  infimum of  $\text{TL}$  measures of the open sets containing it, and also equals the supremum of  $\text{TL}$  measures of the

closed sets contained in it. Let  $E$  be any Borel subset of  $A$ . We obtain

$$\mu'(E) = \inf \{ \mu'(G) \mid G \supset E, G \text{ open} \} \geq \inf \{ \phi^{**}(G) \mid G \supset E, G \text{ open} \} = \phi^{**}(E).$$
(34)

(The inequality comes from (2).) Also, if  $E$  is any Borel subset of  $E$ , we obtain

$$\mu''(E) = \sup \{ \mu''(F) \mid F \subset E, F \text{ closed} \} \leq \sup \{ \phi^{**}(F) \mid F \subset E, F \text{ closed} \} = \phi^{**}(E).$$
(35)

(The inequality comes from (3).)

$\phi^*$  satisfies all constraints (4), according to (34), and all constraints (5), according to (35). Hence it is feasible, hence optimal.

qed

What happens if we allow  $\mu'(A)$  to be greater than  $\mu''(B)$ ? That is, we consider the more general case in which the capacity of sources can exceed the requirement of sinks. Surprisingly, Theorem 7 breaks down:

Theorem 8: There is an abstract Transportation problem satisfying all the premises of Theorem 7, except that  $\mu'(A) > \mu''(B)$ , for which no optimal solution exists.

Proof: Let there be just one source,  $a_1$ , of capacity 1. Let there be a countable number of sinks:  $B = \{b_1, b_2, \dots\}$  with requirements identically zero. Let every subset of  $B$  be open. Let the unit transport cost function be:  $r(a_1, b_n) = \frac{1}{n} - 1$ . One easily verifies that all the premises of Theorem 7 hold (except, of course, that  $\mu'(A) = 1$ ,  $\mu''(B) = 0$ ). Yet there is no optimal flow, since if  $n$  is the smallest integer for which  $\phi\{a_1, b_n\} > 0$ , shifting this flow to the sink  $b_n$  reduces costs, while the identically zero flow is the worst of all.

qed

There are, however, certain conditions under which we can still assert the existence of an optimal flow in the slack capacity case.

Theorem 9: Let the premises of Theorem 7 be altered as follows.

$$(i) \mu'(A) \geq \mu''(B) \quad (\text{replacing the stronger condition } \mu'(A) = \mu''(B))$$

(ii)  $\mathcal{K}(B, \mathcal{T}')$  is compact and metrizable. (replacing the weaker condition  $\mathcal{K}(B, \mathcal{T}')$  is separable and topologically complete).

Then an optimal solution exists to the abstract transportation problem

Proof: The place where the proof of Theorem 7 breaks down if we replace  $\mu'(A) = \mu''(B)$  by an inequality, is in relation (3a), where we cannot assert that

$$\phi(A \times (B \setminus K'')) + \phi((A \setminus K') \times B) = \mu''(B \setminus K'') + \mu'(A \setminus K'),$$

since Theorem 2 does not apply. However, if  $B$  itself is compact, we can replace  $K''$  by  $B$ , to obtain

$$\phi(A \times B \setminus K' \times B) = \phi((A \setminus K') \times B) \leq \mu'(A \setminus K') < \epsilon. \quad (36)$$

Hence the set of feasible solutions is again uniformly tight, and the proof proceeds exactly as in Theorem 7. QED

Theorem 10: Let the premises of Theorem 7 be altered as follows:

$$\mu'(A) \geq \mu''(B), \text{ and } r \text{ is non-negative.}$$

Then an optimal solution exists to the abstract transportation problem.

We just outline the proof, rather than carrying out the somewhat tedious details. Given the original problem, we construct a new problem by adding an extra point  $e_2$  to the destination space  $B$ . We specify  $\mathcal{K}(B, \mathcal{T}')$  so that every flow to this point does not to be paid. We extend the topology  $\mathcal{T}'$

by specifying that  $G \circ \varphi$  is to be open iff  $G$  is open in  $T$ ? We extend  $R$ . measure  $\mu''$  by specifying that the requirement for the singleton set  $\{z\}$  is to be  $\mu(A) - \mu''(B)$ . Finally, we extend the function  $r$  by specifying that  $r(x, z) = 0$  for all  $x \in A$ .

This new problem satisfies all the premises of Theorem 7, including the condition that total capacity = total requirement. (Incidentally, this construction is the abstract form of the standard trick of adding an artificial sink to take up the slack in an inequality-constrained (unit) transportation problem.) Hence there exists an optimal flow  $\phi^{**}$  in it. Let  $\phi^*$  be this flow restricted to the original product space  $A \times B$ . We claim that  $\phi^*$  is optimal for the original problem.

To show this, let  $\phi$  be any feasible flow for the original problem. Using the Radon-Nikodym theorem, we can show the existence of another feasible flow,  $\tilde{\phi}$ , which satisfies  $\tilde{\phi} \leq \phi$ , and satisfies

$$\tilde{\phi} \leq \phi, \quad (37)$$

and satisfying the destination requirements exactly:

$$\tilde{\phi}(A \times E) = \mu''(E), \text{ for all } E \in \Sigma''. \quad (38)$$

It follows from (38) that  $\tilde{\phi}$  has an feasible extension,  $\tilde{\phi}$ , to the extended space  $A \times (B \circ \varphi)$  which is feasible for the extended modified transportation problem. Finally, putting everything together, we obtain

$$\int r d\phi^* = \int r d\phi^{**} \leq \int r d\tilde{\phi} = \int r d\phi \leq \int r d\phi, \quad (39)$$

which proves that  $\phi^*$  is optimal.

(The inequalities in (39) follow from the fact that  $r(x, z) = 0$ ; the first inequality follows from the optimality of  $\phi^{**}$  in the modified transportation problem; the last inequality follows from  $r \geq 0$  and (37).)

Finally, we give two results which extend the scope of Theorem 7 considerably.

Theorem 11: Let the premises of Theorem 7 be weakened to read: ~~Assumptions~~ are Borel subsets of separable and topologically complete spaces. Then there still exists an optimal solution. (A), (T') and (B), (T)

Proof: The only place where topological completeness is used in the proof of Theorem 7 is to imply that  $\mu^1$  and  $\mu^2$  are tight measures. But any measure on a space satisfying the weakened premise above is necessarily tight. (see Parasaethy, p 29-30). QED

In practical terms, Theorem 11 means that existence can be asserted not only when the origin-destination spaces, A and B, are Euclidian spaces of arbitrary finite dimension; but also when they are more or less arbitrary subsets.

Theorem 12: Let the premises of Theorem 7 be satisfied. Let  $\lambda$  and  $\nu$  be two given measures on  $(A \times B, \Sigma' \times \Sigma'')$ , and let  $f_{\text{feas}}, b_1, b_2$  be required to satisfy not only (4) and (5), but to lie between  $\lambda$  and  $\nu$ :

$$\lambda(E) \leq \phi(E) \leq \nu(E), \text{ for all } E \in \Sigma' \times \Sigma''. \quad (40)$$

Then, if there exists a feasible flow satisfying (4), (5), and (40), there exists an optimal flow for these constraints.

Proof: As far as it goes, the proof of Theorem 7 applies without change, except that we must explicitly assume the existence of a feasible solution to get started, since Theorem 1 is not available. Thus, we

Know there exists a sequence  $\phi_1, \phi_2, \dots$  of feasible solutions which converges weakly to a measure  $\phi^*$  satisfying (4) and (5), ~~which~~<sup>and</sup> which achieves the infimum of the objective function (6). It remains to show that  $\phi^*$  satisfies (46). This can be done in exactly the same way that the satisfaction of (4) and (5) are proved; namely, we show that

$$\nu(G) \geq \phi^*(G) \quad (41)$$

for any open set  $G \subset A \times B$ , and that

$$\lambda(F) \leq \phi^*(F) \quad (42)$$

for any closed set  $F \subset A \times B$ , by the same arguments leading to (32) and (33). Then, since  $\Sigma' \times \Sigma''$  is the Borel field of the metrizable space  $(A \times B, \tau' \times \tau'')$ , the inequalities (41) and (42) can be extended to all Borel sets of  $A \times B$ , by the arguments of (34) and (35). Thus (46) is satisfied,  $\phi^*$  is feasible to the more restrictive problem, hence optimal to it. ~~and~~

<sup>2</sup>Also an unlimited number of further constraints of the form  $\phi(G_i) \leq \alpha_i$  or  $\phi(F_i) \geq \beta_i$  may be imposed, where  $G_i$  and  $F_i$  are open and closed sets, respectively, in  $A \times B$ . The proof that feasibility implies optimality is exactly as in theorem 12: just put the subscript  $i$  in lines (41) and (42).

## 6. Existence of Potentials

We have seen that, if  $\phi$  and  $(p, q)$  are feasible to their respective problems, and  $(p, q)$  is a measure potential to  $\phi$ , then  $\phi$  is optimal. Now, we want to tackle the converse (and much more difficult) problem: If  $\phi$  is optimal, is there a dual-feasible pair of functions  $(p, q)$  which is a measure potential to  $\phi$ ?

Actually, as we have mentioned, our results do not produce measure potentials directly, but a related property called a topological potential. We proceed to define this.

Let the quadruple  $(A, \mathcal{T}, \Sigma, \mu)$  be, respectively, a set  $A$ , a topology  $\mathcal{T}$  over  $A$ , a sigma-field  $\Sigma$  over  $A$ , and a measure  $\mu$  on  $\Sigma$ . (We do not necessarily assume that  $\mathcal{T} \subset \Sigma$ , as we have been doing up to now.) Set  $E^x$  is a neighborhood of point  $x \in A$  iff there is an open set  $G$  such that  $x \in G$  and  $G \subset E$ .  $x$  is a point of support of the measure  $\mu$  iff every measurable neighborhood of  $x$  has positive  $\mu$ -measure. The set of all points of support is called the support of  $\mu$ .

Definition. Let  $\phi$  be feasible for the abstract transportation problem (4)-(5), and  $(p, q) \geq 0$  feasible for the dual problem (15).  $(p, q)$  is a topological potential for  $\phi$  iff the following three conditions are satisfied:

If  $(x, y) \in A \times B$  is a point of support of  $\phi$ , then

$$q(y) - p(x) = r(x, y). \quad (43)$$

If  $x \in A$  is a point of support of  $(\mu' - \phi')$ , then

$$p(x) = 0. \quad (44)$$

If  $y \in B$  is a point of support of  $(\phi'' - \mu'')$ , then

$$q(y) = 0. \quad (45)$$

In (43),  $(x, y)$  being a point of support of  $\phi$  refers, of course, to the product space, so that the quadruple used in defining the concept would be  $(A \times B, \mathcal{T}' \times \mathcal{T}'', \Sigma' \times \Sigma'', \phi)$ . In (44),  $\phi'$  is the left-marginal measure of  $\phi$ , so that  $(\mu' - \phi')$  is the measure of unused capacity of the sources; the corresponding quadruple is  $(A, \mathcal{T}', \Sigma', \mu' - \phi')$ . In (45),  $(\phi'' - \mu'')$  is the measure of the oversupply above requirements.

arriving at  $\mathbb{H}$ , sinks; the corresponding quadruple is  $(B, \mathcal{I}^*, \Sigma^*, \phi^*, \mu^*)$ .

This same definition also serves for the pair of equality-constrained programs, except that  $(\mu, \gamma)$  need not be non-negative. Note also that for equality constraints, (44) and (45) are automatically fulfilled, so that they may be omitted from the definition. (This follows from the fact that, for equality constraints,  $(\mu^* - \phi^*)_e$  and  $(\phi^* - \mu^*)_e$  are identically zero, and therefore have no points of support; (44) and (45) are thus vacuously true.)

(43) - (45) have as much claim to generalize the "complementary slackness" conditions of duality theory as do the corresponding conditions (23) - (25) for measure potentials. Indeed, all three concepts coincide for the finite case (with all subsets open and measurable).  $(x, y)$  being a point of support of  $\phi$  generalizes the notion in the finite case that there is a positive flow from origin  $x$  to destination  $y$ . The complementary slackness condition requires in this case that the dual relation for the pair  $(x, y)$  be fulfilled with equality, and this is exactly what (43) requires. Again, if there is unused capacity at a source, the complementary slackness condition requires that the dual variable be zero, just as relation (44) does. Relation (45) is a generalization of the analogous condition for oversupplied sinks.

It is of interest to find conditions under which a topological potential will also be a measure potential, for this, combined with the other results of the present section, will guarantee that an optimal solution of the primal problem implies an optimal solution to the dual such that the two problems have the same value. We need the following topological concept.

Definition. A topological space has the strong Lindelöf property iff, for every collection of open sets  $\mathcal{G}$ , there is a countable subcollection  $\mathcal{G}' \subseteq \mathcal{G}$  such that  $\cup \mathcal{G}' = \cup \mathcal{G}$ .

Any subset of Euclidean  $N$ -space — indeed, any separable metrisable space — has the strong Lindelöf property, so that it includes most cases of practical interest. We now have:

Theorem B: If  $(p, q)$  is a topological potential for  $\phi$ , and the product space  $(A \times B, \tau' \times \tau'')$  has the strong Lindelöf property, then  $(p, q)$  is a measurable potential for  $\phi$ .

\*Proof: First we show that (43) implies (23). A point  $(x, y)$  such that  $q(y) - p(x) < r(x, y)$  is not a point of support of  $\phi$ , according to (43); hence it has a measurable neighbourhood  $N(x, y)$  of  $\phi$ -measure zero.

There is an open set  $G(x, y)$  such that  $(x, y) \in G(x, y) \subset N(x, y)$ .

Consider the collection  $\mathcal{G}$  of all these open sets, one for each point  $(x, y)$  for which the strict inequality holds:  $q(y) - p(x) < r(x, y)$ . By the strong Lindelöf property, there is a countable subcollection  $\{G_1, G_2, \dots\}$  whose union equals  $\cup \mathcal{G}$ . Let  $\{N_1, N_2, \dots\}$  be the neighbourhoods in which these  $G$ -sets are respectively contained. We then have:

$$\{(x, y) \mid q(y) - p(x) < r(x, y)\} \subset (\cup \mathcal{G}) = (G_1 \cup G_2 \cup \dots) \subset (N_1 \cup N_2 \cup \dots). \quad (46)$$

Hence

$$\phi \{ (x, y) \mid q(y) - p(x) < r(x, y) \} \leq \phi (N_1 \cup N_2 \cup \dots) \leq \phi(N_1) + \phi(N_2) + \dots = 0, \quad (47)$$

and this yields (23).

In the equality-constrained case, the proof is completed, since (44) and (45) are automatically fulfilled. In the inequality-constrained case, we may have  $(p, q) \geq 0$ , and we now show that (44) implies (24) and (45) implies (25).

First, it is easily verified that the compact spaces  $(A, \tau')$  and  $(B, \tau'')$  inherit the strong Lindelöf property from the product space.

From this point, the proofs copy II. above reasoning exactly. We consider II. set of points  $x$  in  $A$  such that  $p(x) > 0$ , find a neighborhood of each one of  $(\mu^1 - \phi')$ -measure zero, duplicate II. reasoning involving open sets, and conclude that

$$(\mu^1 - \phi') \{x \mid p(x) > 0\} = 0, \quad (48)$$

which is II. same as (24). Similarly, starting from II. point  $y$  in  $B$  such that  $q(y) > 0$ , we find neighborhoods of  $(\phi'' - \mu'')$ -measure zero, and conclude.  $\square$

$$(\phi'' - \mu'') \{y \mid q(y) > 0\} = 0, \quad (49)$$

which is II. same as (25).

QED

A condition for the opposite implication to hold is easier to find and to prove:

Theorem 14: If  $(p, q)$  is a measure potential for  $\phi$ , and each of II. three sets: (1)  $\{(x, y) \mid q(y) - p(x) < r(x, y)\}$ ; (2)  $\{x \mid p(x) > 0\}$ ; (3)  $\{y \mid q(y) > 0\}$  is open in its respective space ((1)  $(A \times B, \tau' \times \tau'')$ , (2)  $(A, \tau')$ , (3)  $(B, \tau'')$ ), then  $(p, q)$  is a topological potential for  $\phi$ . (In the equality-constrained case, it is sufficient for the first set to be open.)

Proof: We will show that (1) if (43) is false, and the first set is open, then (23) is false; (2) if (44) is false, and II.

Proof: We will show that, if (43), (44), (45), respectively, is false, and the first, second, third set, respectively, is open, then (23), (24), (25), respectively, is false.

Suppose (43) is false. Then there is a point of support  $(x_0^0, y_0)$  of  $\phi$  in which  $q(y_0) - p(x_0^0) < r(x_0^0, y_0)$ . The set  $\{(x, y) \mid q(y) - p(x) < r(x, y)\}$ , being open by assumption, is a neighborhood of  $(x_0^0, y_0)$ ; it is also measured,

hence it has positive  $\phi$ -measure, which is to say that (23) is false.

This already proves the theorem for the equality-constrained case. For the inequality-constrained case, we have  $(p, q) \geq 0$ . The reasoning is the same:

Suppose (24) is false. Then there is a point of support  $x^*$  of  $(\mu^* - \phi')$  for which  $p(x) > 0$ . The set  $\{x \mid p(x) > 0\}$  is measurable and open, hence  $(\mu^* - \phi')(\{x \mid p(x) > 0\}) > 0$ , contrary to (24).

Similarly for (45) and (25). (end)

Note: neither of these theorems makes any assumption about the relations between the topologies and sigma-fields.

We now come to the main business of this section, which is to construct a topological potential associated with a given optimal solution to the abstract transportation problem. We shall concentrate on the equality-constrained case, which is somewhat easier to deal with, and indicate later what happens when we go to inequalities. The assumptions we have to be made to carry through the construction are quite moderate; the proofs, unfortunately, are rather long. We begin by proving a basic lemma, which is then applied to the proof of the main result.

Lemma 3: Let  $(A, \Sigma', \mu')$ ,  $(B, \Sigma'', \mu'')$  and  $r$  be as in the Transportation problem, (4)-(6), where however, <sup>✓</sup>we let  $\phi$  be an optimal solution for <sup>↙ this problem.</sup> which satisfies ~~all constraints with equality~~. Also assume that there are topologies  $\gamma'$  over  $A$ ,  $\gamma''$  over  $B$ , such that  $\gamma' \subset \Sigma'$ ,  $\gamma'' \subset \Sigma''$ , and  $r$  is ~~a~~ continuous with respect to  $\gamma' \times \gamma''$ . (We need not assume with equality: let  $\gamma' \times \gamma'' \subset \Sigma' \times \Sigma''$ ).

Then, if  ~~$a_1, \dots, a_n$~~  are any  $n$  points of  $A$ ,  $b_1, \dots, b_n$  any  $n$  points of  $B$  (not necessarily distinct in either case), such that  $(a_i, b_j)$  are in the support of  $\phi$  for  $(i=1 \dots n)$ , it follows that

$$a_1 b_1 + a_2 b_2 + \dots + a_n b_n \leq a_1 b_2 + a_2 b_3 + \dots + a_{n-1} b_n + a_n b_1. \quad (50)$$

(where we have abbreviated  $r(x_i, y_j)$  as  $x_i y_j$ , a notation we shall use throughout this section.)

Proof: Choose a positive number  $\epsilon$ . There are  $n$  open sets,  $L_1, \dots, L_n$  in  $A$ , and  $n$  open sets  $M_1, \dots, M_n$  in  $B$ , with the following properties:

$$\text{Q} \quad a_i \in L_i, \quad b_i \in M_i \quad (i=1, \dots, n),$$

$$\text{Q1} \quad x_i y_j > a_i b_j - \epsilon \quad \text{for all } x_i \in L_i, y_j \in M_j \quad (i=1, \dots, n), \quad (51)$$

$$\text{Q2} \quad x_i y_j < a_i b_{j+1} + \epsilon \quad \text{for all } x_i \in L_i, y_j \in M_{j+1} \quad (i=1, \dots, n) \quad (52)$$

(where we write  $M_1$  for  $M_{n+1}$ ,  $b_{j+1}$  for  $a_{j+1}$ ).

To see this, note that, by the continuity of  $r$ , there are open sets about  $a_i$  and  $b_i$  such that Q1 is satisfied, and open sets about  $a_i$  and  $b_{i+1}$  such that Q2 is satisfied. This yields two open sets about each of the points  $(a_1, \dots, a_n, b_1, \dots, b_n)$ . The intersection of these two satisfy Q1 and Q2 simultaneously.

$$\text{Let } c = \frac{1}{n} \min_i [\phi(L_i \times M_i)]. \quad \text{is positive, since } \exists \delta,$$

$c$  is positive, since  $L_i \times M_i$  is a measurable neighborhood of  $(a_i, b_i)$ , a point of support of  $\phi$ .

We now alter the  $\phi$  by adding to it  $n$  measures  $\phi_i^*$  ( $i=1, \dots, n$ ) and subtracting from it another  $n$  measures  $\phi_i^{**}$  ( $i=1, \dots, n$ ). These are defined as follows on measurable rectangles  $E \times F$  ( $E \in \Sigma'$ ,  $F \in \Sigma''$ ).

$$\phi_i^{**}(E \times F) = \frac{c \phi((E \times F) \cap (L_i \times M_i))}{\phi(L_i \times M_i)}. \quad (i=1, \dots, n) \quad (54)$$

$$\phi_i^*(E \times F) = \frac{c \phi((E \cap L_i) \times M_i) \phi(L_{i+1} \times (F \cap M_{i+1}))}{\phi(L_i \times M_i) \phi(L_{i+1} \times M_{i+1})}. \quad (i=1, \dots, n) \quad (55)$$

(1 is to be substituted by  $n+1$  in the formula for  $\phi_i^*$ .)

It is easy to see that (52) defines a measure; it is, in fact, proportional to  $\phi$  in the rectangle  $L_i \times M_i$ , and zero outside it. (53) is zero outside the rectangle  $L_i \times M_i$ ; and is in "product-measure" form on the rectangle. A standard extension theorem assures us that it also extends to a measure on  $\Sigma' \times \Sigma'$ .

We claim that the altered flow,  $\phi + \sum_{i=1}^n (\phi_i^* - \phi_i^{**})$ , remains feasible in the transportation problem with equality constraints. First we note that

$$\phi_i^*(E \times B) = \phi_i^{**}(E \times B) = \frac{c\phi((E \cap L_i) \times M_i)}{\phi(L_i \times M_i)}, \quad (i=1 \dots n) \quad (56)$$

so that the marginal condition (ii) remains satisfied. Also

$$\text{Also } \phi_{i=1}^*(A \times F) = \phi_{i=1}^{**}(A \times F) = \frac{c\phi(L_i \times (F \cap M_i))}{\phi(L_i \times M_i)}, \quad (i=1 \dots n) \quad (57)$$

( $n$  is to be substituted by zero in  $\phi_0^*(A \times F)$ ).

Adding up over all changes again leads to cancellation, so that the

marginal conditions (ii) remain satisfied.

It remains to show only that the altered flow is non-negative everywhere. The only negative summands appear in the rectangles  $L_i \times M_i$ . If the measurable set  $E$  is contained in a certain number of these rectangles, the quantity

$$c\phi(E) \sum \frac{1}{\phi(L_i \times M_i)} \quad \text{is subtracted} \quad (58)$$

is subtracted. (Here the summation extends over those  $i$  for which  $E \subset L_i \times M_i$ ). From the definition of  $c$ , this quantity cannot exceed  $\phi(E)$ , the original flow value. Hence non-negativity is preserved. This shows that the altered flow is feasible.

Since  $\phi$  is optimal, the change in transportation cost induced by  $\sum_{i=1}^n (\phi_i^* - \phi_i^{**})$  must be non-negative. Thus

$$\sum_{i=1}^n \int_{A \times B} r d\phi_i^* \geq \sum_{i=1}^n \int_{A \times B} r d\phi_i^{**}, \quad (57)$$

Now  $\phi_i^*$  is zero outside tl. rectangle  $L_i \times M_{i+1}$ ; on that rectangle, tl. inequality (52) applies; hence

$$\int_{A \times B} [a_i b_{i+1} + \epsilon] d\phi_i^* \geq \int_{A \times B} r d\phi_i^* \quad (i = 1, \dots, n). \quad (68)$$

$$(b_{n+1} \equiv b_1)$$

Similarly,  $\phi_i^{**}$  is zero outside tl. rectangle  $L_i \times M_i$ ; on that rectangle, tl. inequality (51) applies; hence

$$\int_{A \times B} [a_i b_i - \epsilon] d\phi_i^{**} \leq \int_{A \times B} r d\phi_i^{**} \quad (i = 1, \dots, n) \quad (69)$$

The left-hand integrands are merely constants; also

$\phi_i^*(A \times B) = \phi_i^{**}(A \times B) = c$ , for all  $i = 1, \dots, n$ ; hence, integrating out the constants, and putting (59), (68), and (69) together, we obtain

$$c(a_1 b_2 + a_2 b_3 + \dots + a_n b_1) + n \epsilon c \geq (a_1 b_1 + a_2 b_2 + \dots + a_n b_n) - n \epsilon c. \quad (60)$$

Since  $c$  is positive, and  $\epsilon$  can be taken arbitrarily small, tl. basic inequality (50) is obtained. QED

Lemma 3 is actually a stronger result than would be obtained if we merely assumed  $\Phi$  to be optimal for tl. inequality-constrained problem (4)-(6). Indeed, suppose  $\Phi$  is optimal for tl. problem (4)-(6). Then it is necessarily also optimal for an equality-constrained subproblem, namely, tl. one in which its own marginals,  $\phi'$  and  $\phi''$ , play the roles of  $\mu'$  and  $\mu''$ , respectively. Therefore, inequality (50) holds for this  $\Phi$ .

We now come to tl. main result. The premises are tl. same as B (in Lemma 3), ~~so that the potentials constructed from the simple functions~~

P and q are "constructed" in the sense that one can write an explicit formula for them.

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(P, q) are constructed which together constitute a topological potential for  $\phi$ . That is, they are bounded and measurable, satisfy the dual feasibility condition (15), and the topological potential condition (43). Note that these are a potential for the equality-constrained problem, and as such are not guaranteed to be non-negative. (44) and (45) are automatically satisfied by the fact that  $\phi$  is an equality-constrained optimum.

First we need a few concepts relating to continuity. Let  $(A, \tau)$  be a topological space, and let  $f$  be a real-valued function with domain A.  $f$  is said to be upper semi-continuous iff every set of  $A$ , born  $\{x \mid f(x) < c\}$  is open ( $c$  being a real number); it is lower semi-continuous iff every set of  $A$ , born  $\{x \mid f(x) > c\}$  is open. If there is a sigma-field,  $\Sigma$ , over A such that  $\tau \subset \Sigma$ , it follows at once from the definition that every upper or lower semi-continuous function is measurable with respect to  $\Sigma$ . Let  ~~$\mathcal{F} = \{f_i\}_{i=1}^{\infty}$~~   $\mathcal{F}$  be a collection of real-valued functions, all with domain A; we define  $\inf \mathcal{F}$  to be the function whose value at the point  $x \in A$  is the infimum of the values assumed by the members of  $\mathcal{F}$  at that point.  $\sup \mathcal{F}$  is defined analogously, by the supremum. It is not hard to show that, if  $\mathcal{F}$  is a collection of continuous functions, then  $\inf \mathcal{F}$  is upper semi-continuous and  $\sup \mathcal{F}$  is lower semi-continuous. Let  $(A \times B, \tau' \times \tau'')$  be a product space, and let  $r$  be a real-valued function with domain  $A \times B$ ;  $r$  is semi-continuous iff, for every positive number  $\epsilon$ , and every  $a \in A$ , there is a set  $G' \in \tau'$  such that  $a \in G'$ , and  $|r(x, y) - r(a, y)| < \epsilon$  for all  $x \in G'$ ,  $y \in B$ , and, for every  $\epsilon > 0$  and every  $b \in B$ , there is a set  $G'' \in \tau''$  such that  $b \in G''$ , and  $|r(x, y) - r(x, b)| < \epsilon$  for all  $x \in A$ ,  $y \in G''$ . Let  $(A, d)$  be a metric space, and let  $f$  be a function with domain A;  $f$  is uniformly continuous iff, for all positive  $\epsilon$ , there is a positive  $\delta$  such that  $d(x_1, x_2) < \delta$  implies  $|f(x_1) - f(x_2)| < \epsilon$ .

Let  $(A, d')$  and  $(B, d'')$  be two metric spaces, and  $r$  a function with domain  $A \times B$ ;  $r$  is uniformly continuous iff, for all positive  $\epsilon$ , there is a positive  $\delta$  such that  $d'(x_1, x_2) < \delta$  and  $d''(y_1, y_2) < \delta$  imply that  $|r(x_1, y_1) - r(x_2, y_2)| < \epsilon$  ( $x_1, x_2 \in A$ , and  $y_1, y_2 \in B$ ).

Theorem 15: Let  $(A, \Sigma', \mu')$ , and  $(B, \Sigma'', \mu'')$ , and  $r$  be as in th. transportation problem with equality constraints, (10), (11), and (6). Let  $\phi$  be an optimal solution for this problem. Assume that there are topologies  $\gamma'$  over  $A$ , and  $\gamma''$  over  $B$ , such that  $\gamma' \subset \Sigma'$ ,  $\gamma'' \subset \Sigma''$ , and  $r$  is continuous with respect to  $\gamma' \times \gamma''$ .

Then there exist functions,  $p$  and  $q$  (with domains  $A$  and  $B$ , respectively) such that  $(p, q)$  is a topological potential for  $\phi$ ; furthermore,  $p$  is lower and  $q$  is upper semi-continuous.

- (i) If, in addition,  $r$  is upper-continuous, then  $p$  and  $q$  are continuous.
- (ii) If, in addition,  $d'$  on  $A \times A$ , and  $d''$  on  $B \times B$ , are metrics for  $\gamma'$  and  $\gamma''$ , respectively, and that  $r$  is uniformly continuous, then  $p$  and  $-q$  are uniformly continuous.

Proof: For any  $a \in A$ , we defin.  $p(a)$  as follows:

(Let  $x$  stand for points of  $A$ ,  $y$  for points of  $B$ , and abbreviat.  $r(x, y) \approx xy$ ).

Consider the class of all finite sequences  $(x_0, y_1, x_1, \dots, y_n, x_n)$  beginning with  $a = x_0$ , having the property that  $(x_i, y_i)$  is a point of support for  $\phi$  ( $i=1, \dots, n$ ). The value of this sequence is defined to be

$$-x_0 y_1 + x_1 y_1 - x_1 y_2 + x_2 y_2 - \dots + x_n y_n. \quad (63)$$

( $n$  is an arbitrary integer; we also allow th. "sequence" consisting of  $x_0$  alone; this is assigned th. value zero.)

$p(a)$  is now defined as the supremum of the values of all such permissible sequences beginning with  $a$ .

Having defined  $p$ , we now define  $q$  as follows:

For any  $b \in B$ ,

$$q(b) = \inf_{x \in A} [p(x) + xb] \quad (64)$$

We claim that  $\mu_1$  pair  $(p, q)$  is a topological potential for  $\phi$ .

First we show that  $p$  is bounded. Clearly  $p \geq 0$ , since the sequence consisting of  $x_n$  alone is permissible, and has value zero.

Let  $(x_0, y_1, x_1, \dots, y_n, x_n)$  be a permissible sequence. According to (53) of Lemma 3,

$$0 \geq x_1 y_1 - x_0 y_1 + x_2 y_2 - \dots + x_n y_n - x_0 y_1 \quad (65)$$

Adding  $x_0 y_1 - x_0 y_1$  to both sides of (65), we get (63) on the right, so that the value of any permissible sequence is bounded above by  $x_0 y_1 - x_0 y_1$ . Let  $M = \sup |xy|$  over  $x \in A, y \in B$ ; since  $r$  is bounded,  $M$  is finite. We have just shown that  $p$  is bounded. In fact

$$2M \geq p \geq 0. \quad (66)$$

It follows from this that  $q$  is bounded. In fact, from (64) and (66),

$$-M \geq q \geq -M. \quad (67)$$

Next we verify (65). In fact,  $q(y) - p(x) \leq xy$  follows at once from the definition of  $q$ ; (64).

Next we verify (63). Let  $(a, b)$  be a point of support for  $\phi$ .

For any  $x \in A$ , we have

$$p(x) \geq -xb + ab + p(a). \quad (68)$$

To see this, note that the right-hand side of (68) is simply

the supremum over all permissible sequences beginning  $(x, y, z, \dots)$ ; hence it cannot exceed  $p(x)$ , which is the supremum over a wider class of permissible sequences. Hence  $p(x) + xy$  attains its minimum at  $x = a$ . Therefore

$$g(y) = p(a) + ab, \quad (69)$$

so that (43) is verified.

It remains only to show that  $p$  and  $g$  are measurable with respect to their sigma-fields,  $\Sigma'$  and  $\Sigma''$ , respectively. We do this by proving the stronger result that  $p$  is lower and  $g$  upper semi-continuous.

Holding  $y$  fixed, and considering  $p(x) + xy$  as a function of  $x$ , with domain  $B$ , we note that it is continuous with respect to  $\gamma'$ , since  $\gamma$  is continuous with respect to  $\gamma' \times \gamma''$ .

$g \in \text{int } \mathcal{P}$ , where  $\mathcal{P}$  is the collection of these functions for all possible values of  $x \in A$ ; hence  $g$  is upper semi-continuous.

As for  $p$ , we first show that, if  $x$  is a point for which  $p(x) > 0$ , then

$$p(x) = \sup_{y \in B} \left[ g(y) - xy \right]. \quad (68)$$

As for  $p$ , we first note that

$$p(x) \geq \sup_{y \in B} \left[ g(y) - xy \right]. \quad (69)$$

This follows at once from the definition of  $g$ , (64). Now let  $x$  be a point for which  $p(x) > 0$ . For any positive  $\epsilon$ , there must be a permissible sequence, beginning  $(x, y_1, x_1, \dots)$ , whose value  $\epsilon$  away from  $p(x)$ :

$$p(x) - \epsilon < -x y_1 + x_1 y_1 + p(x_1) \quad (70)$$

Therefore

$$p(x) - \epsilon < g(y_1) - xy_1, \quad (71)$$

From th. fact that  $(x_i, y_i)$  is a point of support of  $\phi$ , together with (67),

From (20) and (21), and th. fact that  $\epsilon$  is arbitrary, we obtain

$$p(x) \leq \sup_{y \in B} [g(y) - xy], \quad (73)$$

whenever  $p(x) > 0$ . Therefore, we have in general

$$p(x) = \max \left\{ 0, \sup_{y \in B} [g(y) - xy] \right\}. \quad (74)$$

Holding  $y$  fixed,  $g(y) - xy$ , considered as a function of  $x$  with domain  $A$ , is continuous. Also the identically zero function is continuous.

$p = \sup F$ , where  $F$  is now the collection of these functions for all possible values of  $y \in B$ , together with the identically zero function; hence  $p$  is lower semi-continuous. QED

~~This completes the proof for~~

Theorem 16: If, in addition to the premises of theorem 15,  $r$  is equicontinuous, then there is a topological potential with  $p$  and  $g$  continuous (in their respective spaces  $(A, \mathcal{T})$  and  $(B, \mathcal{T}')$ , of course).

If, in addition,  $d'$  on  $A \times A$ , and  $d''$  on  $B \times B$  are metrics such that  $r$  is uniformly continuous, then  $p$  and  $g$  are uniformly continuous.

Proof: We use the same construction as above, and show that it has these properties. Let  $r$  be equicontinuous. We show that  $g$ , defined by (64), is such that the set  $\{y | \alpha < g(y) < \beta\}$  is open for all real numbers  $\alpha < \beta$ . Let  $g(b)$  lie in this set, and choose  $\epsilon$  small enough so that

$$\alpha < g(b) - \epsilon < g(b) + \epsilon < \beta \quad (75)$$

There is an open neighborhood  $G''$  of  $b$  such that  $|xy - xb| < \epsilon$  for all  $x \in A$ ,  $y \in G''$ . It follows from (64) that  $|g(y) - g(b)| \leq \epsilon$

for all  $y \in G''$ ; hence, by (75),  $G'' \subset \{y \mid a < g(y) < b\}$ ; hence the latter set is open, so that  $g$  is continuous.

Analogous reasoning applies to the function

$$\tilde{p}(x) = \sup_{y \in B} [g(y) - xy], \quad (76)$$

which is therefore continuous; hence  $p = \max(0, \tilde{p})$  is continuous.

To prove the second part, assume that  $r$  is uniformly continuous with respect to the metric spaces  $(A, d')$  and  $(B, d'')$ . For any positive  $\epsilon$ , there is a  $\delta$  such that  $d''(y_1, y_2) < \delta$  implies  $|xy_1 - xy_2| < \frac{\epsilon}{2}$  for all  $x \in A$ ; hence, again from (64),  $|g(y_1) - g(y_2)| < \epsilon$  whenever  $d''(y_1, y_2) < \delta$ , so that  $g$  is uniformly continuous.

Analogous reasoning applies to (76), so that  $\tilde{p}$  is uniformly continuous. Hence  $p = \max(0, \tilde{p})$  is uniformly continuous.  qed

Just as in lemma 3, the conclusions of theorems 15 and 16 apply also if  $\phi$  is optimal for the inequality-constrained Transportation problem, since it is then also optimal on equality-constrained subproblem.

What has not been shown is that, in this case, there are functions  $p, q$  which are also non-negative and satisfy (44) and (45).<sup>10</sup> <sup>10</sup> In explicit investigations make it likely that the construction in theorem 15 (or a slight modification of it, perhaps) will in fact have these properties as well, in the inequality-constrained case. At the present moment, however, this is conjectural.

We conclude with a theorem that wraps up several of our previous results.

Theorem 17: Let  $(A, \Sigma', \mu')$  and  $(B, \Sigma'', \mu'')$  and  $r$  be as in the abstract Transportation problem with equality constraints. Let  $\phi$  be

optimal to the problem. In addition, suppose that one can find topologies  $\mathcal{T}'$  over  $A$  and  $\mathcal{T}''$  over  $B$ , such that (i)  $\mathcal{T}' \subset \Sigma'$  and  $\mathcal{T}'' \subset \Sigma''$ ; (ii)  $\mathcal{T}' \times \mathcal{T}''$  has the strong Lindelöf property; (iii)  $r$  is continuous with respect to  $\mathcal{T}' \times \mathcal{T}''$ .

Then there exist functions  $(p, q)$  with domains  $A, B$ , which are feasible and optimal to the dual problem, and for which the value of the dual equals the value of the primal.

Proof:  $(p, q)$  constructed in theorem 15 <sup>is a</sup> topological potentials to  $\phi$ .

Hence, by the strong Lindelöf property and theorem 13, it is a measure potential. Hence, by theorem 6, the value of the dual equals the value of the primal, so that  $(p, q)$  is dual optimal. □

\*One final comment. The fact that  $\phi$  is optimal enters into the proof of theorem 15 in a tenuous fashion. It is used only to prove lemma 3, and lemma 3 is used only to prove that  $p$  is bounded. Hence, if  $\phi$  is any feasible flow, not known to be optimal, and we carry out the construction of theorem 15, and it turns out to be bounded, then  $(p, q)$  is a topological potential to  $\phi$ . If, in addition, the strong Lindelöf property holds to  $\mathcal{T}' \times \mathcal{T}''$ , then the reasoning in the proof of theorem 17 assures us that  $\phi$  is, in fact, optimal. Thus, in this circumstance, boundedness of  $(p, q)$  constructed in theorem 15 is both necessary and sufficient for optimality of  $\phi$ .

## 7. Application to Thüring Systems

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